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Solutions to Linear Algebra and Its Applications ...

The fourth equation is $x_4 = -5$, and the other equations do not contain the variable x_4 . The next two steps should be to use the variable x_3 in the third equation to eliminate that variable from the first two equations. In matrix notation, that means to replace R_2 by its sum with 3 times R_3 , and then replace R_1 by its sum with -5 times R_3 . 6.

1.1 SOLUTIONS - Aerostudents

of C. CD. For mental computation, the 2 1 1 4 2 3 1(1) 25 14 7 6 row-column rule is probably easier to use than the definition. 7 5 1 2 14 0 10 1 2 16 10 1 2 0 1 2 2.

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The fourth rule is correct if we define f^{-1} to be the inverse of the function $f(\cdot)$, because then the rule $f(g(x)) = x$ states that $f^{-1}(f(x)) = x$, assuming an inverse exists. The seventh rule is not true in general since $c(x+y)$ is $c f(g(x))$ and $c x + c y$ is $c f(g(x))$ which are not the same in general.

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4 Section 1.11.1.23 a Substituting $y = 5$ yields the system $7x + y = 5$, $2x + y = 0$, $6x + 8y = 5$, $6x + 3y = 0$. There are infinitely many solutions, of the form $(x, y) = (2t, t)$, where t is an arbitrary real number. b Proceeding as in part (a), we find $(x, y) = (3t, t)$.

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